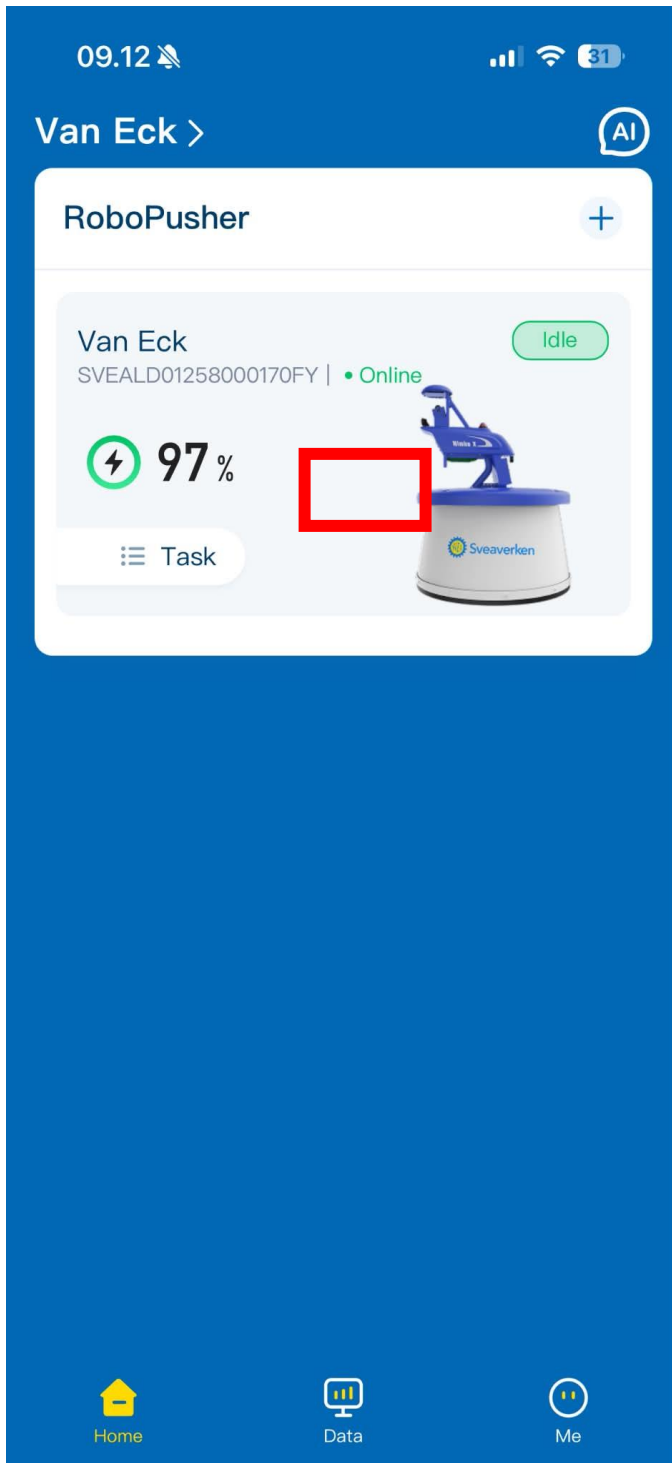
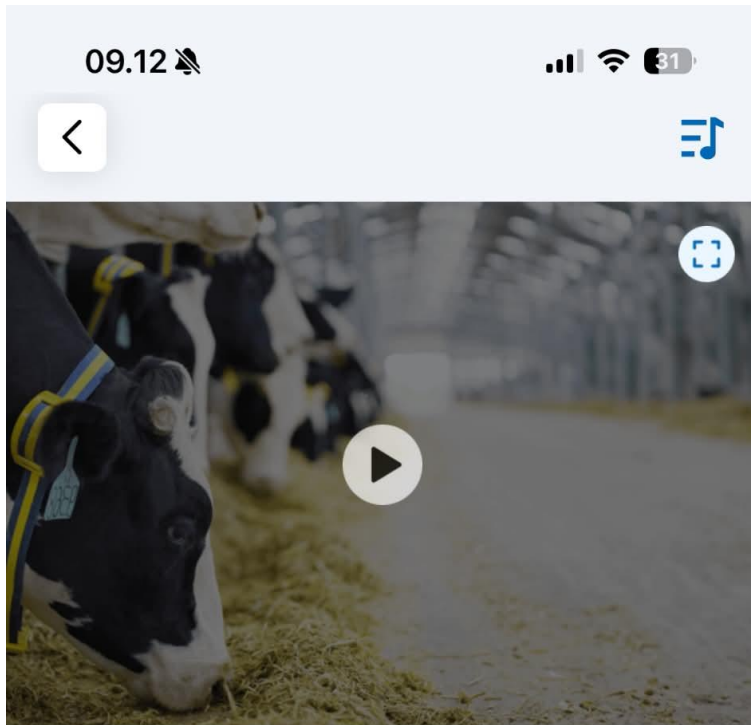


Sådan foretager du manuel start af din robot.

Vær opmærksom på, at når du laver manuel start af robotten, så kører den med en standard distance mellem robotten og køernes fanggitter. Skal robotten køre med en bestemt distance, skal den igangsættes via en opgave.

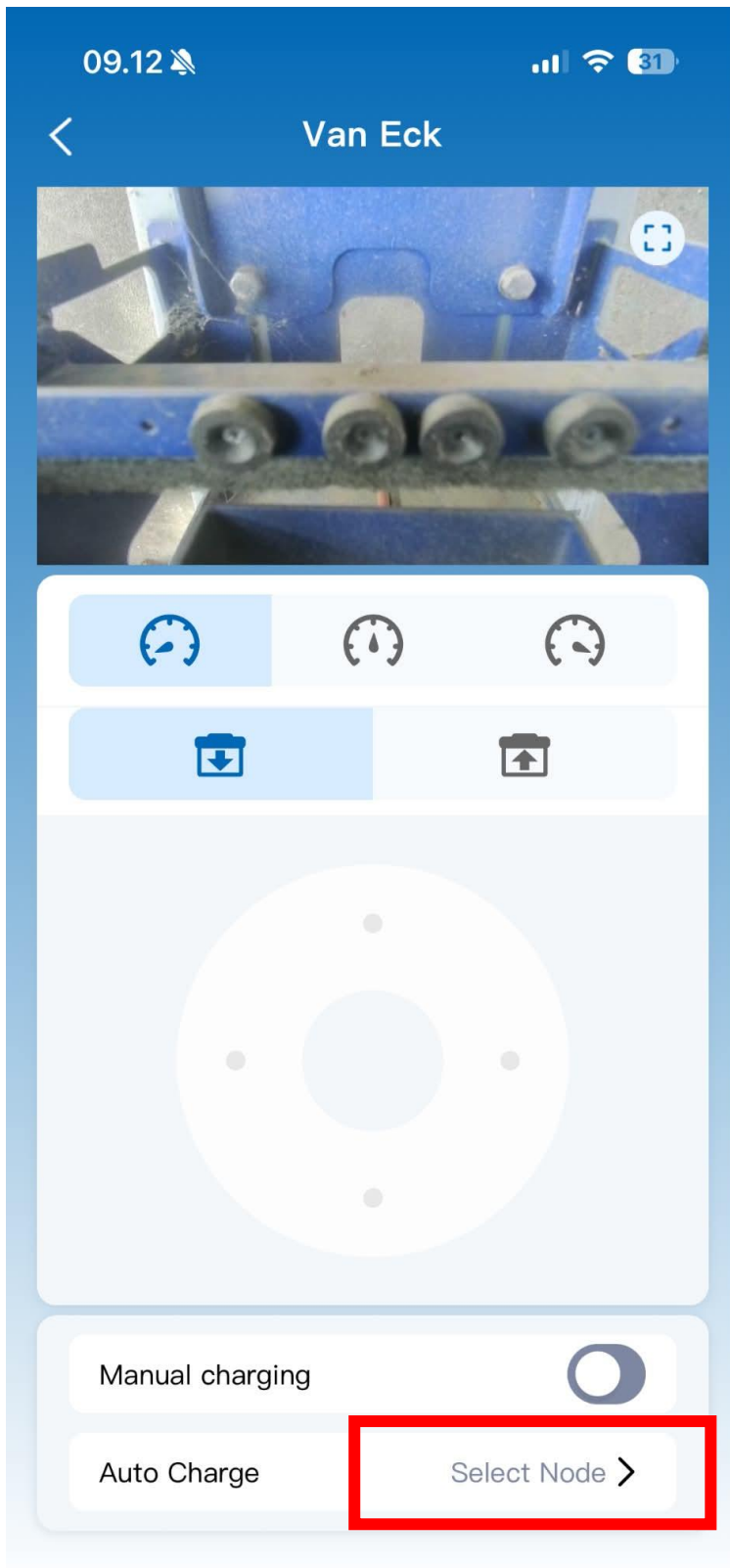


Trin 1

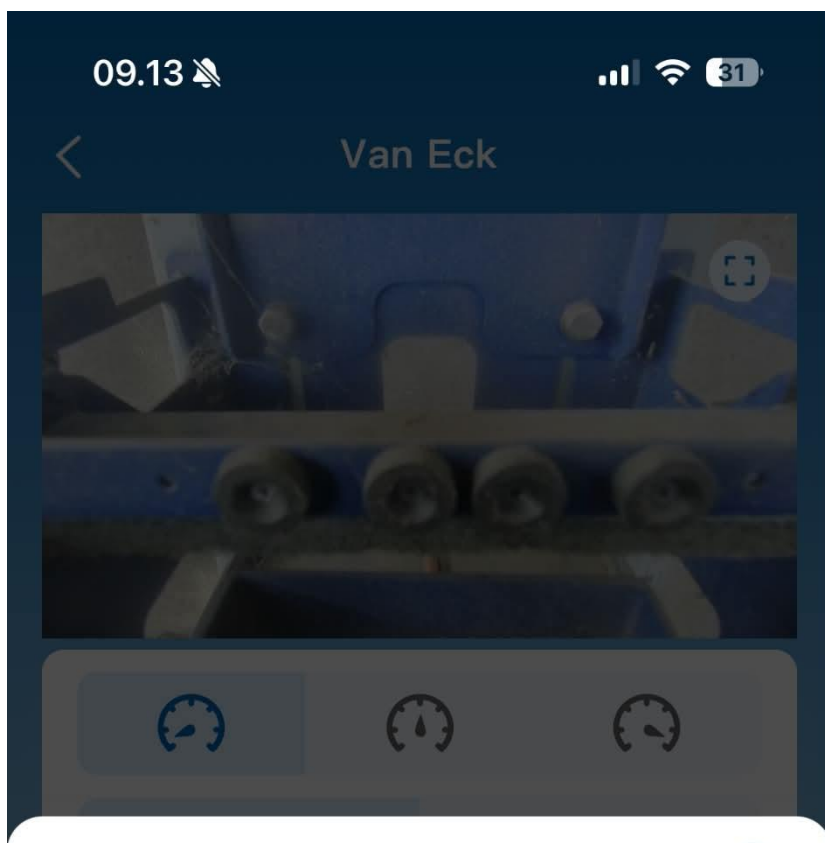


 **Van Eck**
SVEALD01258000170FY

Idle Status	Nimbo X Plus Product Model
Normal Camera Status	2.0.1.32 Smart Module
 One-click Return	 Remote Control
 Restart Device	 Restart Battery



Trin 3



Trin 4

Select Node



*Path

Select here.

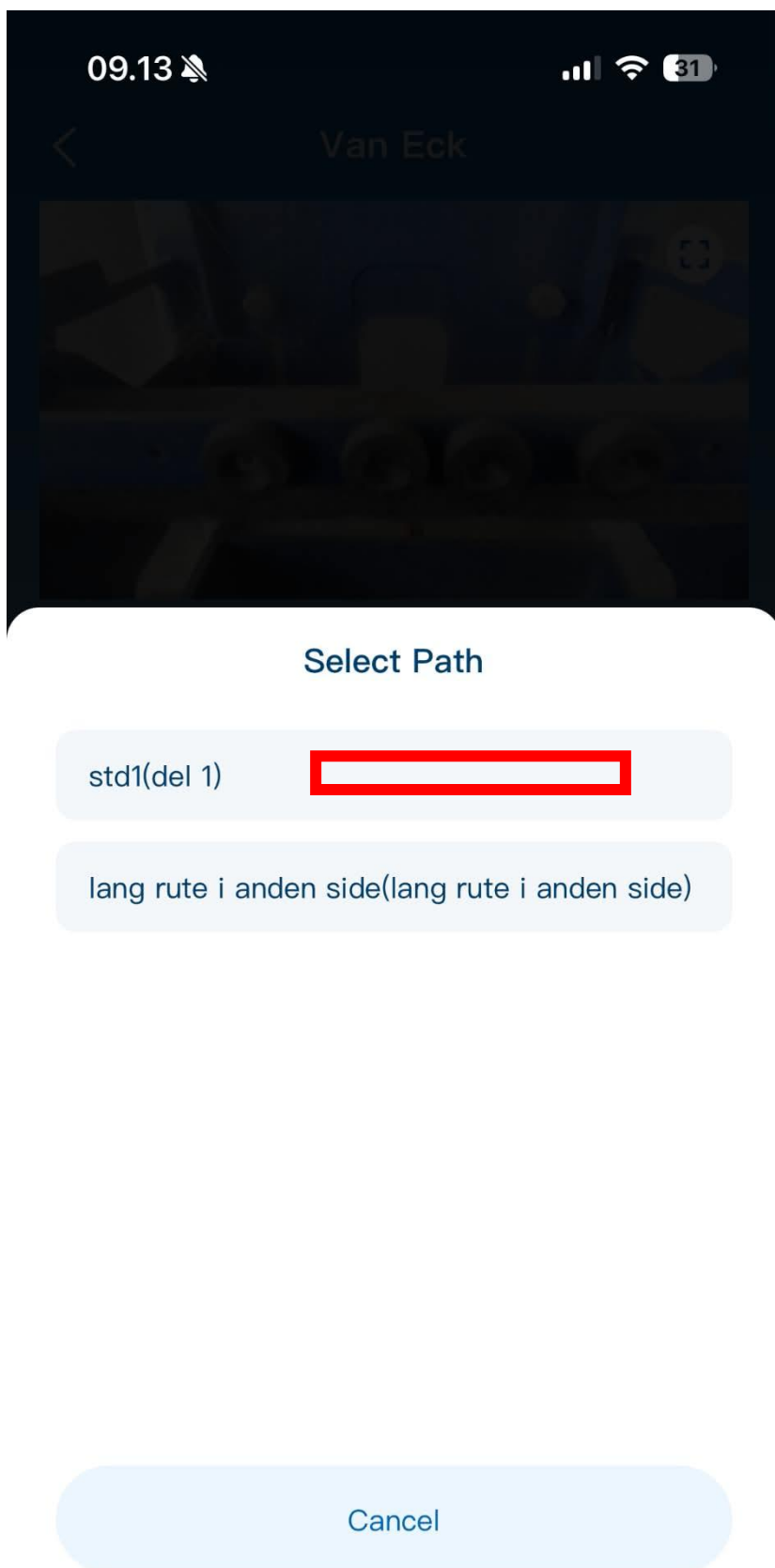
*Node

Select here.

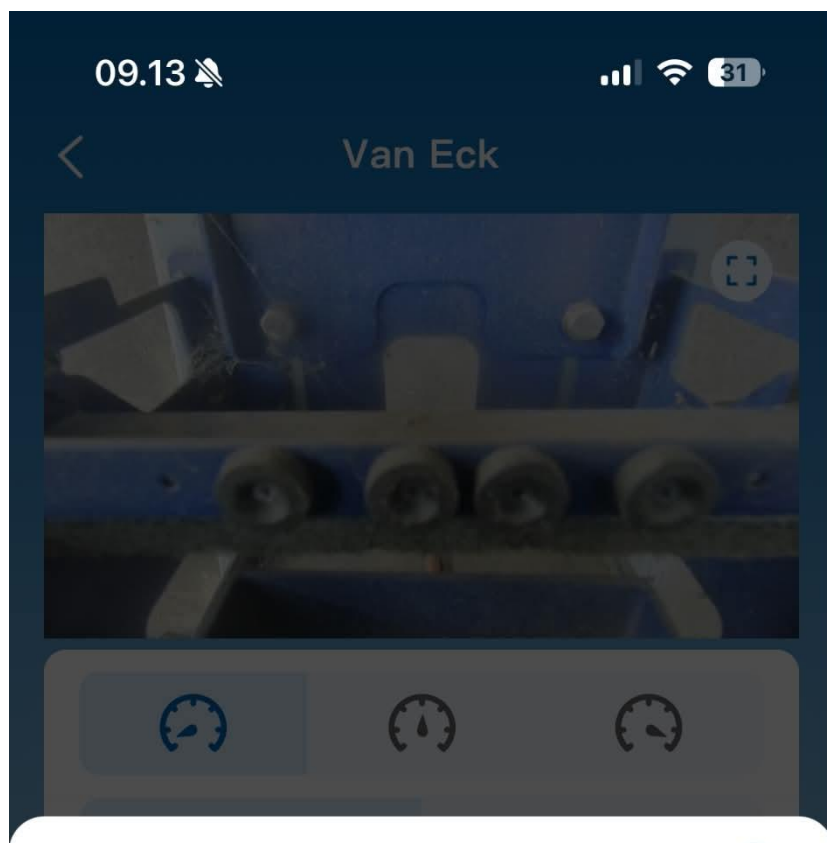


Cancel

OK



Trin 5



Trin 6

Select Node



*Path

std1(del 1)



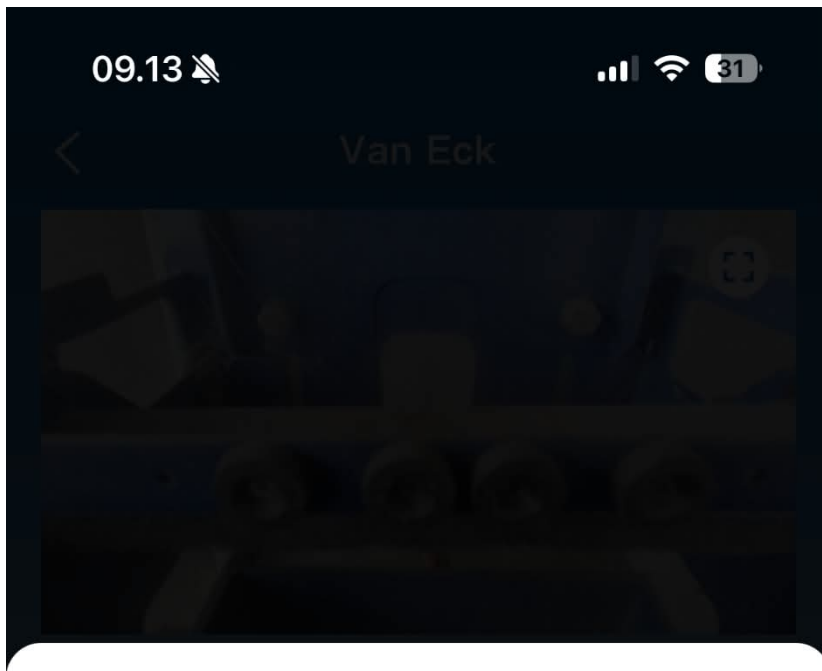
*Node

Select here.



Cancel

OK



Select Path

1. Lidar return

2. Drum lifting

3. Turning

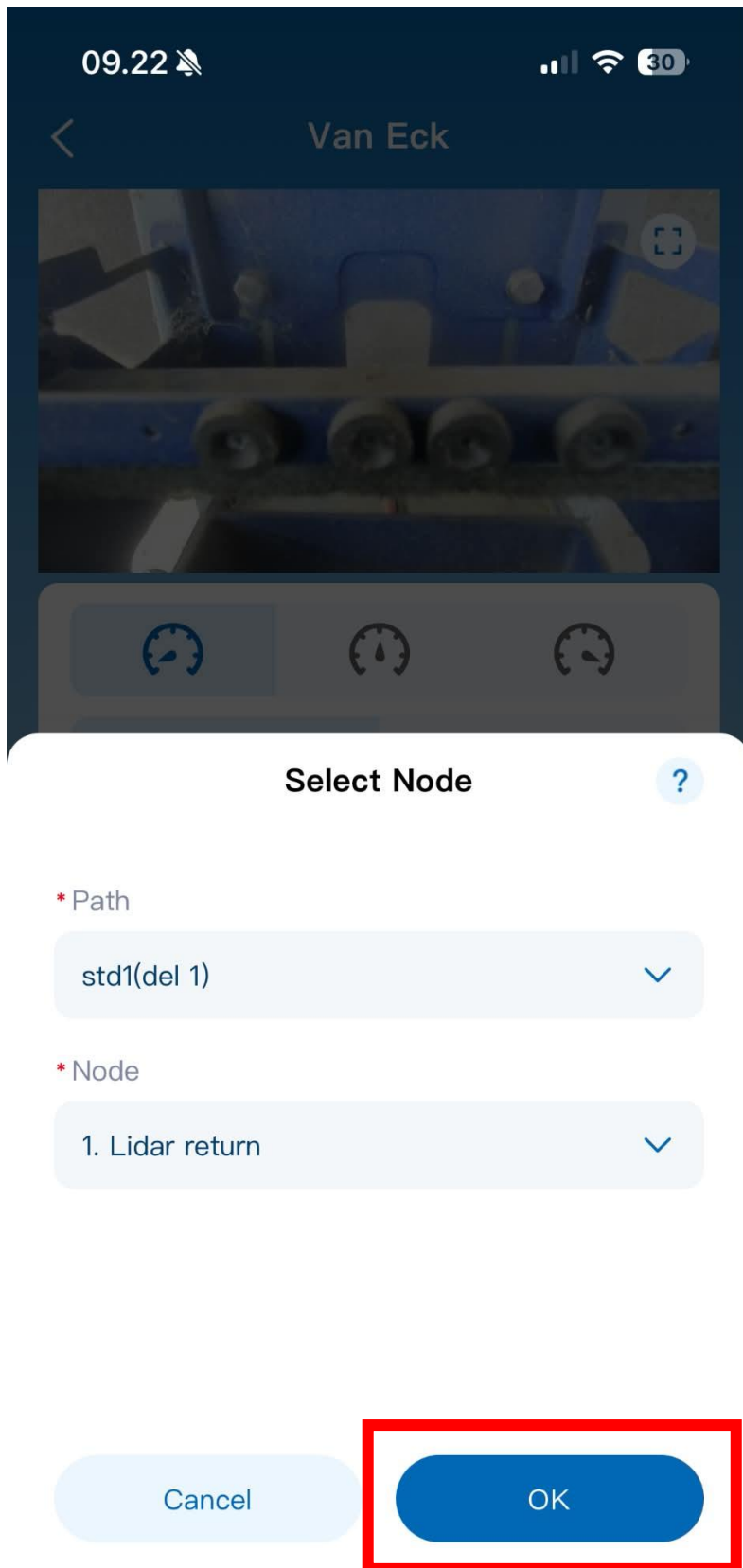
4. Lidar cruise mode

5. Drum lifting

6. Lidar push

Cancel

Trin 7



Trin 8

Nu kører robotten i den del af stalden, som du har valgt i trin 5.